Velodyne LiDAR®

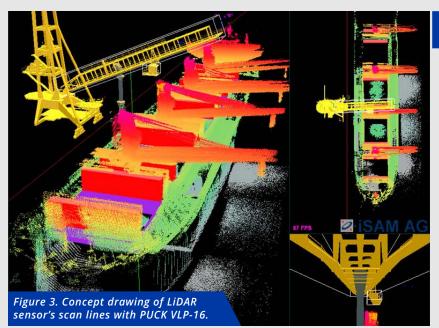
Velodyne LiDAR Sensors - The Future of bulk material ship transfers

Velodyne LiDAR's Puck 3D LiDAR sensors are utilized in automotive vehicles to generate 3D maps/images in real-time traffic environments. These same sensors provide wide area coverage and may be utilized to automate ports to load and unload containers from ships to trucks. Three-dimensional LiDAR sensors provide better, faster measurement data which is easier to model in a more productive way.



Current conveyor transfer equipment does not optimize the space in the cargo hold because the pile. Three-dimensional LiDAR sensors have a limited view of the pile. Three-dimensional LiDAR sensors are changing automation's best practices in bulk material ship transfers by offering a complete spatial view.

	Current Solution	Future Solution
Required Sensor Types	2D LiDAR Scanners	3D LiDAR Sensor
Data Measurement	ON/OFF (2D LiDAR) Distance, Calibrated Reflectivity Values, Rotation Angles and Timestamps	
Data Output	Several Communication Protocols (Ethernet, RS232, etc.)	UDP Packets (with timestamps) via Ethernet Protocol
Sensor Coverage Area	Multiple Sensor Technologies Required; Specific Sensors Perform Individual Tasks Over a Limited Area.	One 3D LiDAR Sensor Performs Multiple Functions and Covers Greater Spatial Area
System Integration	Difficult to Implement and Modify for Future Systems	Easy Modification and Implementation Process for Future Product Upgrades.



Velodyne LiDAR[•] Sensor Advantage:

› Lowers Total Cost of Ownership

- Reduced Sensor Count
- Shortens/Simplifies Design
- and Implementation Time
- Detailed 3D Images for Vehicle/Object/Container Profiling
 - Full Surround View in both Horizontal and Vertical Fields
 - Fast Identification of Vehicles, Objects and Containers
 - Easilly identify objects with a retro-reflective coating
- Fast On-site Commissioning Time
- > Flexibility in Use of Pure Measurement Data

Real-Time 3D LiDAR Sensors

The Puck[™] and HDL-32E provide high definition 3-dimensional information about the surrounding environment.

Parameters	VLP-16	HDL-32E	Benefit
Range	100 m (>300 feet)	100 m (>300 feet)	Detects objects at farther distances.
# of Channels	16	32	Visualize actual scanned objects.
Horizontal Field of View	360°	360°	Detect and maintain visibility continuously.
Horizontal Resolution (Azimuth)	0.1° to 0.4°	0.1° to 0.4°	No laser beam gaps for accurate measurements.
Vertical Field of View	30° (-15° to +15°)	40° (-30.67° to +10.67°)	Follow objects as they move.
Vertical Resolution	2.0°	1.33°	Determine potential hazards before they enter critical scan line.
Rotation Rate	5 Hz to 20 Hz	5 Hz to 20 Hz	Reliable Time-of-Flight Measurement Techniques.
Accuracy	±3.0 cm (±1.2")	±2.0 cm (±0.8")	Measure stationary and moving objects accurately.
Data Output Information	UDP Packets • Distance Measurements • Calibrated Reflectivities • Rotation Angles • Time Stamps (µs resolution)	UDP Packets • Distance Measurements • Calibrated Reflectivities • Rotation Angles • Time Stamps (µs resolution)	Provides a wealth of information to distinguish different types of vehicles and objects.
Data Output	Single Return Mode: 300k points/s Dual Return Mode: 700k points/s	Single Return Mode: 695k points/s Dual Return Mode: 1,390k points/s	More than 4x data output from competing solutions.
Operating Voltage	9 V to 18 V (Directly to Sensor) 9 V to 32 V (Thru Interface Box)	9 V to 18 V (Directly to Sensor) 9 V to 32 V (Thru Interface Box)	Standard operating voltage range.
Power Consumption	8 W	12 W	Low energy consumption, decreases operating expenses.
Enclosure Rating	IP67	IP67	Operates in wet and cold environments.
Operating Temperature	-10°C to +60°C	-10°C to +60°C	Works in hot and cold weather conditions.
Size	Ø103 mm x 72 mm (Ø4.1" x 2.8")	Ø85 mm x 144 mm (Ø3.6" x 5.68")	Smaller size allows for easier placement.
Weight	830 g (1.8 lbs)	1 kg (2.2 lbs)	Lower weight for bigger mounting brackets.

Contact us for a video or onsite product demonstration. Email: sales@velodyne.com Phone: +1-408-465-2899

www.velodynelidar.com